RMS and Standard deviation

Gemini AI Pro 2.5

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Root mean square. What is the usefulness of this metric?

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The Root Mean Square (RMS) is a statistical measure used to find the **effective** value or magnitude of a varying quantity. Unlike a simple average, it's especially useful for sets of numbers that include negative values or fluctuate, such as waves.

Its primary usefulness comes from its method: 1. **Square:** Square each value in the set. This makes all values non-negative (e.g., -10 becomes 100) and gives greater weight to larger values. 2. **Mean:** Calculate the average (mean) of these squared values. 3. **Root:** Take the square root of that mean. This returns the metric to the original unit of measurement (e.g., from Volts² back to Volts).

This "squaring" step is key. A simple average of a fluctuating signal like an AC (alternating current) sine wave would be zero, which is not useful. The RMS value, however, gives a meaningful measure of its strength.

Usefulness in Physics & Engineering

The most common application is in **electrical engineering** to describe alternating current (AC) voltage or current.

- AC Power: An AC voltage (like in your wall outlet) constantly fluctuates between a positive and negative peak.
- The Problem: A simple average would be zero, but the current is clearly doing work (e.g., lighting a bulb).
- RMS Solution: The RMS value tells you the equivalent DC (direct current) value that would deliver the same amount of power to a resistor.

Example: A 120V AC outlet in the US means its **RMS voltage** is 120 Volts. This provides the same power and heating effect as

a steady 120V DC battery. The *peak* voltage of that AC signal is actually much higher (about 170V).

This is why RMS is used for rating electrical appliances, fuses, and circuit breakers—it provides a standard, meaningful way to compare the power of AC and DC.

Usefulness in Statistics & Data Science

In statistics, the concept is most famously used as the **Root Mean Square Error (RMSE)**. This metric is a standard way to measure the accuracy of a model's predictions.

- The Problem: When building a model (e.g., to predict house prices), you need to know how "wrong" its predictions are. Your model will be off by different amounts for different houses (the "errors" or "residuals").
- RMSE Solution: The RMSE aggregates these errors into a single number.
 - It squares each error (so +\$10k and -\$10k errors are treated equally).
 - It averages these squared errors.
 - It takes the square root to show the error in the original units (e.g., dollars).

Example: If a house price prediction model has an RMSE of \$15,000, it means the model's predictions are, *on average*, about \$15,000 away from the actual sale prices.

Because it squares the errors, the RMSE penalizes large errors more heavily than smaller ones. This makes it particularly useful when large mistakes are highly undesirable.

This video provides a good explanation of how RMS values are calculated for different waveforms. * Average and RMS Calculations

http://googleusercontent.com/youtube_content/0 https://www.youtube.com/watch?v=TDgTYsgz4UI

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What is the link between RMS and Standard Deviation?

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Of course. The link is very direct: **Standard Deviation** *is* a specific type of Root Mean Square.

To be precise, the Standard Deviation is the RMS of the deviations from the mean. The RMS you asked about previously is the RMS of the actual values themselves.

Let's break that down.

1. The Core Difference

- Root Mean Square (RMS): Measures the magnitude of a set of values, centered around zero.
- Standard Deviation (SD): Measures the "spread" or "dispersion" of a set of values, centered around their own mean (average).

The critical link: If the mean of your dataset is exactly zero, the RMS and the Standard Deviation will be identical.

2. A Look at the Formulas

This is where the connection becomes obvious. Let's look at a set of values $x_1, x_2, ..., x_n$ and their mean, \bar{x} .

Root Mean Square (RMS) You square the values, find their mean, and take the root.

$$RMS = \sqrt{\frac{x_1^2 + x_2^2 + \dots + x_n^2}{n}}$$

Standard Deviation (σ) You first find the *deviation* (error) of each value from the mean $(x_i - \bar{x})$. Then, you square those **deviations**, find their mean, and take the root.

$$\sigma = \sqrt{\frac{(x_1 - \bar{x})^2 + (x_2 - \bar{x})^2 + \dots + (x_n - \bar{x})^2}{n}}$$

See the pattern? Both are a "Root" of a "Mean" of "Squares." The only difference is *what* you are squaring: * **RMS:** Squares the **values**. * **SD:** Squares the **distance from the mean**.

3. The Mathematical Relationship

There is a formal equation that ties RMS, Standard Deviation (σ) , and the Mean (\bar{x}) together:

$$RMS^2 = \sigma^2 + \bar{x}^2$$

Or, written out:

 $(RMS \text{ of values})^2 = (Standard Deviation})^2 + (Mean of values})^2$

This formula perfectly illustrates their relationship:

- If the Mean (\bar{x}) is 0: The equation becomes $RMS^2 = \sigma^2$, so $RMS = \sigma$. This is why they are identical for signals with no DC offset (like a pure AC sine wave).
- In all other cases: The RMS value will always be larger than the Standard Deviation because it also accounts for the energy or magnitude of the mean.

In engineering terms, RMS represents the **total power** of a signal, while the Standard Deviation (σ) represents the power of the **fluctuating (AC) part** of the signal, and the Mean (\bar{x}) represents the power of the **steady (DC) part**.

This video discusses the calculation of RMS for different types of signals, which relates to these concepts. * RMS Value Calculations

http://googleusercontent.com/youtube_content/1 https://www.youtube.com/watch?v=TDgTYsgz4UI

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This code works on a vector. Please convert it to work on a matrix, and explain carefully how the column slicing operations work.

```
function mystd(x)
    n = size(x,1)
    mu = mymean(x)
    sigma = sqrt(1/n * sum((x.-mu).^2))
    return sigma
end;
```

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Here is the code converted to work on a matrix, calculating the standard deviation for each column.

The Converted Code

The main change is adding dims=1 to the sum function and updating mymean to also work column-wise. This assumes you want the standard deviation of each column, which is the standard convention in statistics.

I've included the necessary mymean function for clarity.

```
"""

Calculates the mean of each column of a matrix x.

Returns a 1xk row vector of means.
"""

function mymean(x::Matrix)

# sum(x, dims=1) sums all rows for each column,
# producing a 1xk row vector.
```

```
# size(x, 1) is the number of rows (n).
    return sum(x, dims=1) / size(x, 1)
end
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Calculates the population standard deviation of each column of a matrix {\tt x}.
Returns a 1xk row vector of standard deviations.
function mvstd(x::Matrix)
    n = size(x, 1) # n = number of rows (observations)
    mu = mymean(x) # mu = 1xk row vector of column means
    # See explanation below for this line
    squared diffs = (x .- mu).^2
    # Sum the squared differences *down the columns* (dims=1)
    # and divide by n to get the variance for each column.
    variance = sum(squared_diffs, dims=1) / n
    # Take the element-wise square root
    sigma = sqrt.(variance)
    return sigma # Returns a 1xk row vector
end
You could also write mystd as a one-liner, just like your original:
function mystd_oneliner(x::Matrix)
    n = size(x, 1)
    mu = mymean(x)
    # The .^ and .- are element-wise. sum(..., dims=1) is column-wise.
    sigma = sqrt.((1/n) * sum((x .- mu).^2, dims=1))
    return sigma
end
```

Explanation of Column-Wise Operations

Your original code used "dot operators" (.-, .^) for element-wise operations on vectors. When moving to a matrix, we combine this with two other concepts: **broadcasting** and **dimensional aggregation**.

This is more efficient than "column slicing" (e.g., writing a for loop over x[:, i]).

Let's break down the key line: sum((x .- mu).^2, dims=1)

Assume x is a 10x3 matrix (10 rows, 3 columns).

- n = size(x, 1) will be 10.
- 1. mu = mymean(x) First, mymean(x) calculates the mean of each column.
 - sum(x, dims=1) sums the 10 numbers in each column, producing a 1x3 row vector.
 - It divides this by n (10) to get the average for each column.
 - mu is now a 1x3 row vector: [mu col1, mu col2, mu col3]
- 2. (x .- mu) Broadcasting (The "Implicit Slicing") This is the most important step. You are subtracting a 1x3 row vector (mu) from a 10x3 matrix (x).

Julia's **broadcasting** feature handles this automatically. It "stretches" (or *broadcasts*) the 1x3 row vector mu to match the 10x3 matrix.

Operationally, it subtracts:

- mu col1 from every element in the 1st column of x.
- mu_col2 from every element in the 2nd column of x.
- mu_col3 from every element in the 3rd column of x.

The result is a new 10x3 matrix of "deviations from the mean." This single operation achieves the same result as a for loop over the columns, but is much faster.

- **3.** (...) $\hat{}$ 2 This is a simple element-wise operation. It squares every deviation in the 10x3 matrix, resulting in a new 10x3 matrix of squared differences.
- **4.** sum(..., dims=1) Dimensional Aggregation This is the final step in getting the variance.
 - sum(...) adds up the numbers.
 - dims=1 tells Julia which dimension to sum along. Dimension 1 is rows.
 - So, sum(..., dims=1) "collapses" the rows by summing them up. It sums all 10 squared differences in each of the 3 columns.
 - The result is a 1x3 row vector containing the total sum of squared differences for each column.

The rest of the function (/ n and sqrt.) then scales this 1x3 vector to get the final standard deviations.

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Please explain the inside of the parenthesis: function mymean(x::Matrix)

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This part (x::Matrix) defines the function's arguments (also called parameters). It can be broken into two parts:

- 1. x: This is the name of the argument. It's a local variable name. When you call the function, like mymean(my_data), the data my_data will be assigned to the variable x inside the function.
- 2. :: Matrix: This is a type annotation.
 - The :: (double colon) operator is used to "assert" or "declare" the type of a variable.
 - Matrix is a built-in Julia type that means "a 2-dimensional array."

What it means together

function mymean(x::Matrix) creates a "contract" or "signature" for this function. It means:

"I am defining a function named mymean that must be called with one argument, and that argument must be a 2D matrix."

Why this is important in Julia

This syntax is the key to Julia's main feature: multiple dispatch.

You can (and often do) create multiple functions with the *same name* but different type annotations:

- function mymean(x::Matrix): Calculates the mean for a 2D matrix (e.g., column-wise).
- function mymean(x::Vector): Calculates the mean for a 1D vector (e.g., a simple average).
- function mymean(x::Number): Just returns the number itself.

When you call mymean(my_data), Julia looks at the type of my_data at runtime and automatically chooses (or *dispatches* to) the correct, specialized version of the function for you.

This makes your code: * Fast: Each version is optimized for its specific data type. * Clear: It's obvious what kind of data the function expects. * Safe: If you call mymean("hello"), Julia will immediately throw a MethodError because you haven't defined a version of mymean that accepts a String.

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So this function cannot be called with a vector?

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That's exactly right. No, that specific function cannot be called with a vector

The signature function mymean(x::Matrix) strictly defines this version of mymean to *only* accept arguments of type Matrix.

If you try to call it with a vector, like mymean([1, 2, 3]), Julia will stop and give you a MethodError. This error basically means, "I looked for a function named mymean that accepts a Vector, but I couldn't find one."

The Solution: Multiple Dispatch

This isn't a problem; it's the intended way Julia works! The solution is to simply define *another* function (a new "method") with the same name but for the Vector type.

You would add this code:

```
Calculates the mean of a 1D vector.
"""
function mymean(x::Vector)
    # The logic for a vector is simpler
    return sum(x) / length(x)
end
```

Now, your code has **two** methods for mymean:

```
    function mymean(x::Matrix)
    function mymean(x::Vector)
```

When you call mymean(my_data), Julia will automatically check the type of my_data and call the correct version for you. This is multiple dispatch, and it's what makes Julia code so clear and efficient.

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So, this means I have to make two function definitions?

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Yes, if you want them to do two different things.

This isn't a limitation; it's the central design feature of Julia. You are defining two **methods** for the *same* generic function mymean.

Why You Want Two Definitions

The two functions have fundamentally different behaviors and return types:

1. mymean(x::Vector)

- Input: A 1D vector (e.g., 10 elements).
- Action: Calculates the mean of all 10 elements.
- Output: One single number (a scalar).

2. mymean(x::Matrix)

- Input: A 2D matrix (e.g., 10 rows by 3 columns).
- Action: Calculates the mean of each column separately.
- Output: A 1x3 row vector (one mean for each column).

Because the behavior (total mean vs. column-wise mean) is different, you provide a separate, optimized definition for each type.

The "Julia Way": Multiple Dispatch

This is called **multiple dispatch**. You are not creating two unrelated functions. You are adding two specific *methods* to the *single concept* of mymean.

When you call mymean(data), Julia will:

- 1. Look at the **type** of data.
- 2. If data is a Vector, it dispatches to your vector version.
- 3. If data is a Matrix, it dispatches to your matrix version.

Your code would look like this:

```
# Method 1: For Vectors
function mymean(x::Vector)
    return sum(x) / length(x)
end

# Method 2: For Matrices (column-wise)
function mymean(x::Matrix)
    return sum(x, dims=1) / size(x, 1)
end

# --- Now you can use both! ---
v = [1, 2, 3, 4]
m = [1 10;
    2 20]

mymean(v) # Calls Method 1, returns 2.5
mymean(m) # Calls Method 2, returns [1.5 15.0]
```

The Alternative (If You Wanted The Same Behavior)

What if you wanted the mean of all elements, whether it's a vector or a matrix?

Then you could write **one** function using AbstractArray (which is the parent type of both Vector and Matrix):

```
# This one function works for both
function my_total_mean(x::AbstractArray)
    return sum(x) / length(x)
end

my_total_mean(v) # Returns 2.5
my_total_mean(m) # Returns (1+2+10+20)/4 = 8.25
```

But since your goal was to get the **column-wise** mean for a matrix, you need the two separate definitions.